A comparative study of the Lasso-type and heuristic model selection methods

I. Savin
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Abstract

This study presents a first comparative analysis of Lasso-type (Lasso, adaptive Lasso, elastic net) and heuristic subset selection methods. Although the Lasso has shown success in many situations, it has some limitations. In particular, inconsistent results are obtained for pairwise strongly correlated predictors. An alternative to the Lasso is constituted by model selection based on information criteria (IC), which remains consistent in the situation mentioned. However, these criteria are hard to optimize due to a discrete search space. To overcome this problem, an optimization heuristic (Genetic Algorithm) is applied. Monte-Carlo simulation results are reported to illustrate the performance of the methods.

Keywords: Model selection, Lasso, adaptive Lasso, elastic net, heuristic methods, genetic algorithms.

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1 Introduction

The model selection process is crucial for the further analysis of any multiple regression model. Picking up too many regressors increases the variance of the constructed model, and taking fewer regressors than needed results in inconsistent estimates. In the last years the least absolute shrinkage and selection operator (Lasso) (Tibshirani 1996) has become a very popular method for simultaneous model selection and parameter estimation.

Among the Lasso’s main advantages are the combination of prediction accuracy and the parsimony of models built. The Lasso-type estimator outperforms simple application of parameter estimation methods (as, e.g., ordinary least squares or method of moments) since it shrinks the coefficients of insignificant regressors towards zero. Hence, the resulting models concentrate on the strongest effects and the total accuracy of the model forecast is increased. In addition, the Lasso solutions are more stable than other subset selection techniques based on the information criteria (IC) and stepwise strategies as, e.g., the general-to-specific approach (PcGets) discussed by Hendry and Krolzig (2005) and its bottom-up alternative (RETINA) analyzed by Perez-Amaral et al. (2003).

Another important advantage of the Lasso is its computational feasibility. Since its computational cost hardly exceeds the complexity of one linear regression (Efron et al. 2004), it is more attractive in comparison to classical model selection strategies that involve more intensive combinatorial search. However, the Lasso-estimator has some limitations. In particular, inconsistent results are obtained for highly correlated regressors (see Section 2).

In the last five years many studies have been devoted to methods revising and improving the initial Lasso concept. Since it is infeasible to describe them all in detail in this short introduction, I name only the most important ones from my perspective: the elastic net (EN) (Zou and Hastie 2005) and the adaptive Lasso (aLasso) (Zou 2006). A special case of the Lasso-type technique with the penalty term’s exponent less than one is analyzed by Knight and Fu (2000).

This study compares the Lasso-type model selection strategies with one
based on IC. In opposition to the Lasso, IC remain consistent even for data
sets with correlated regressors. The IC’s main constraint is the computa-
tional burden associated with the search for the optimum solution even for a
moderate number of regressors. However, as is shown, e.g., by Maringer and
Winker (2009), thanks to recent advances in heuristic optimization methods
mimicking natural evolution processes, there are efficient algorithms able to
select a model with at least a good approximation to the IC’s global opti-
num. To the best of my knowledge, this article is the first that compares the
Lasso-type and the heuristic model selection methods. An important contri-
bution of this study is the demonstration that in certain situations (e.g., if
the portion of relevant predictors in a given data set is large) subset selection
methods via heuristic algorithms can outperform the Lasso-type solutions.

The remainder of the paper proceeds as follows. Section 2 introduces
both the Lasso-type methods and the heuristic model selection technique.
Section 3 provides the results of our Monte-Carlo analysis and Section 4
illustrates an application to a cross-country growth model. Finally, Section 5
concludes.

2 Model selection strategies

2.1 Least absolute shrinkage and selection operator

The least absolute shrinkage and selection operator (Lasso) was introduced
by Tibshirani (1996). Initially suggested as a constrained version of the ordi-
nary least squares estimator, Lasso can be applied to a variety of estimation
methods including, e.g., VAR-models (Hsu et al. 2007) and GMM-estimators
(Caner 2009). Numerous applications of this technique can be found in
medicine, economics and other scientific fields (Foster et al. 2008, Hastie
et al. 2009).

Let us consider the basic approach to the model selection problem for the
following regression function:

\[ y = \alpha + X^{\text{opt}} \beta + \varepsilon, \]

(1)
where \( \alpha \) is an \( n \)-vector with all elements equal, \( X \) is an \( n \times k \) matrix of \( k \) regressors and their values for \( n \) observations, \( \beta \) is a \( k \times 1 \) vector of their coefficients and \( \varepsilon \) is an \( n \times 1 \) vector of residuals.

In (1) \( X^{opt} \) refers to the subset of all regressors one seeks to identify. This might be the ‘true’ model in a Monte-Carlo simulation set-up or an optimal approximation to the unknown real data generating process. Let us assume that the predictors have been standardized to have mean zero and unit length, and that the response has mean zero:

\[
\sum_{i=1}^{n} y_{i} = 0, \quad \sum_{i=1}^{n} x_{ij} = 0, \quad \sum_{i=1}^{n} x_{ij}^2 = 1, \quad i = 1, \ldots, n, \quad j = 1, \ldots, k.
\]  

Hence, one can omit \( \alpha \) without loss of generality. Then, the Lasso objective function can be presented as follows:

\[
\hat{\beta}_{\text{Lasso}} = \arg \min_{\beta} \left[ \| y - X \hat{\beta} \|_2^2 + \lambda \| \hat{\beta} \|_1 \right].
\]  

While the first term in the right part of equation (3) is just the residual sum of squares (RSS), the second term with \( \lambda > 0 \) is the amount of shrinkage the Lasso applies to the sum of the absolute values of the coefficients. Hence, the Lasso can be referred to as a special case of the Bridge regression approach (Frank and Friedman 1993) imposing an upper bound on the \( L^q \)-norm of the parameters (0 < \( q \) < \( \infty \)) with \( q = 1 \):

\[
\| \hat{\beta} \|_q = \left[ \sum_{j=1}^{k} |\beta_j|^q \right]^{1/q}.
\]  

Equivalently to (3), the Lasso chooses \( \hat{\beta} \) by minimizing RSS subject to a bound \( t \) on the \( L^1 \)-norm of the parameters:

\[
\hat{\beta}_{\text{Lasso}} = \arg \min_{\beta} \| y - X \hat{\beta} \|_2^2 \quad \text{subject to} \quad \| \hat{\beta} \|_1 \leq t
\]  

\(^1\lambda \) is a tuning parameter that can be defined using a data-driven method as, e.g., cross-validation.
with \( t \) being inversely proportional to \( \lambda \).

In the following the intuition behind the Lasso algorithm (a modification of the LARS algorithm) is briefly described. One starts with an empty model (all coefficients are set to zero) and identifies the predictor \( x_\zeta \) out of the full set of \( k \) regressors (\( I \)) most correlated with the response \( y \):

\[
\hat{\zeta} = \arg \max_{\zeta} |\hat{c}_\zeta|, \quad \text{where} \quad \hat{c}_\zeta = X'_I(y - \hat{\mu}_0)
\]

with \( \hat{\mu} = X_A \hat{\beta} \) being a prediction vector of regressors included in the model (respectively, one starts with \( \hat{\mu}_0 = 0 \)).

Transferring the \( \zeta \)-regressor to the ‘solution path’ (\( A \)) one needs to ensure that the next predictor \( x_\zeta \) to be included in \( A \) (\( x_\zeta \) is the most correlated covariate with the current residual) has as much correlation with \( y_2 - \hat{\mu}_1 \) as \( x_\zeta \). In other words, \( y_2 - \hat{\mu}_1 \) has to 'bisect' the angle between \( x_\zeta \) and \( x_{\zeta} \), so that \( c_\zeta(\hat{\mu}_1) = c_\zeta(\hat{\mu}_1) \). To this end, one increases \( \hat{\mu}_0 \) in the direction of \( x_\zeta \):

\[
\hat{\mu}_1 = \hat{\mu}_0 + \hat{\gamma}_\zeta x_\zeta.
\]

In the LARS algorithm \( \hat{\gamma}_\zeta \) is taken as the smallest positive value, so that another regressor can be included in the solution path fulfilling the condition of ‘equally correlated regressors’. Starting from the third predictor one employs an 'equiangular vector' (\( u_A \)) in \( \hat{\mu}_1 \) instead of the previous included regressor (\( x_\zeta \)). The 'equiangular vector' is a unit vector constructed based on all covariates already transferred to \( A \) (\( X_A \)) generating equal angles with the regressors.

In addition, the algorithm enforces that in each step \( \psi = 1, 2, ..., \Psi \) (when a new regressor is included in \( A \)) the sign of all predictors’ estimates (\( s_A \)) in the Lasso solution \( \hat{\beta} \) must agree with the sign of the current correlation:

\[
\hat{c}_{\psi, A} = X'(y - \hat{\mu}_{\psi-1}) \quad \text{for} \quad s_A = \text{sign}(\hat{c}_A) = \text{sign}(\hat{\beta}_A).
\]

---

\(^2\)For a detailed (technical) explanation of all steps see Efron et al. (2004).

\(^3\)\( \Psi \) is an additional stopping criteria limiting the maximum number of steps. In the LARS algorithm \( \Psi = 8k \) that is usually enough for all \( k \) to be included in \( A \).
If the restriction (8) is violated, the corresponding regressor \( x_\rho \) is removed from \( A \) and, therefore, is removed from the calculation of the next equiangular direction \((u_A)\). However, later \( x_\rho \) can be re-included in \( A \), but the order of predictors in the solution path will be already different. This process continues until all \( k \) regressors are transferred to \( A \), thus, ensuring that at each step \( \psi \) only one regressor can be included or excluded from \( A \), \( \max(\psi) \geq k \).

As a result, one obtains a piecewise-linear solution path in the tuning parameter \( \lambda \in [0, \infty) \) with all \( \hat{\beta} \)'s set to zero at \( \lambda = \infty \) and equal to the OLS estimate at \( \lambda = 0 \) (all \( k \) covariates included).

Then, in order to select a single Lasso-solution out of \( A \), tenfold cross-validation minimizing the prediction error (PE) of \( \hat{\beta} \) is applied:

\[
PE = E \left( y - X\hat{\beta} \right)^2.
\] (9)

In (9) the original sample is randomly partitioned into ten subsamples, whereas nine subsamples are used as training data to obtain \( \hat{\beta} \) and a single subsample is retained as validation data for testing the model. The process is repeated ten times and the results from the folds are averaged. Alternatively, bootstrap resampling or the Stein’s unbiased estimate of risk can be used (Tibshirani 1996).

The pseudocode of the procedure described is stated in Algorithm 1.

**Algorithm 1** Pseudocode for the Lasso.

1: Generate an empty solution \( \beta_0 \), initialize \( k, \Psi, A \) and \( I \)
2: while \( I \neq \emptyset \) and \( \psi \leq \Psi \) do
3: Select max\( |c_\zeta| \), transfer \( x_\zeta \) from \( I \) into \( A \)
4: Identify \( \hat{\mu} \) that \( c_\zeta(\hat{\mu}) = c_\zeta(\hat{\mu}) \)
5: for \( x_\rho \subset A \) do
6: Estimate \( (\hat{c}_A) \) and \( (\hat{\beta}_A) \)
7: if sign\( (\hat{c}_A) \neq \text{sign}(\hat{\beta}_A) \) then
8: Transfer \( x_\rho \) from \( A \) into \( I \)
9: end if
10: end for
11: end while
12: Identify \( \hat{\beta}_{\text{Lasso}} \) with \( \min(PE) \)

Thanks to the shrinkage parameter, the Lasso solution has a parsimony
property, i.e., only a subset of resulting predictors in (3) has non-zero coefficients. This feature of the Lasso technique increases the total accuracy of the model forecast and makes the selected model more interpretable.

However, the Lasso-estimator has substantial limitations. First, the Lasso is inconsistent when \( k \gg n \) (overdetermined linear system). In this case, the Lasso algorithm can identify not more than \( n - 1 \) (standardized) predictors (Efron et al. 2004). Second, it is also not able to identify all 'true' predictors in a data set with pairwise highly correlated regressors (Zou and Hastie 2005). The latter limitations can be referred to as the 'irrepresentable condition' stated by Zhao and Yu (2006, p. 2544). As a result of the two constraints, the Lasso estimations can be biased.

Let us assume that in the 'true' model \( \beta^{true} = \{\beta_1, ..., \beta_r, \beta_{r+1}, ..., \beta_k\} \) all non-zero coefficients are located between 1 and \( r \). Then the matrix \( C = \frac{1}{n} X_n' X_n \) can be expressed in a block-wise form:

\[
C = \begin{pmatrix}
C_{11} & C_{12} \\
C_{21} & C_{22}
\end{pmatrix}
\] (10)

with \( C_{11} \) being an \( r \times r \) matrix.

For the Lasso to be consistent, it is essential that

\[
|C_{21}C_{11}^{-1}s| < 1
\] (11)

with \( s = (\text{sign}(\beta_1), ..., \text{sign}(\beta_r))' \) and \( 1 \) is a \((k - r) \times 1\) vector of ones so that the inequality (11) holds element-wise.

In other words, none of the irrelevant regressors (the amount of its covariate) can be represented by the covariates of 'true' predictors. Otherwise the \( L^q \)-norm constraint on the regression coefficients has to be smaller than 1 \((q < 1)\).

The condition (11) is known as the (weak) irrepresentable condition. It is always satisfied, e.g., for \( k = 2 \) or for the orthogonal design (uncorrelated regressors). For more details on situations where the irrepresentable condition holds, see Zhao and Yu (2006, p. 2548).
2.2 Lasso modifications

In the last five years a large amount of studies has been devoted to methods revising and improving the initial Lasso concept:

- the elastic net (EN) that uses a combination of the Lasso and ridge regression penalty (Zou and Hastie 2005);
- the adaptive Lasso (aLasso) applying different amounts of shrinkage for each regression coefficient (Zou 2006);
- the generalized $L^q$-norm (Bridge) regression approach with $0 < q < 1$ (fulfilling the condition \((11)\)) analyzed by Knight and Fu (2000).

In the following I concentrate on two main extensions of the Lasso: EN and aLasso. The reason for this choice is twofold. First, the selected extensions are particularly designed to deal with the Lasso limitations stated above. Second, in contrast to the Bridge approach, the two methods operate in a continuous space and, therefore, are computationally more efficient.

2.2.1 Elastic net

In many fields of application it is still common that only a small number of reliable observations (historical data) exists for a large series of potential predictors ($k \gg n$). Numerous examples of this problem can be found in genetic engineering (e.g., gene expression data) or in chemometrics (e.g., fluorescence spectra) (Frank and Friedman 1993). In addition to the lack of degree of freedom, these models include a set of highly correlated predictors. The latter problem can be encountered even for independent regressors $X_k$ as long as $k \gg n$ (see Fan and Lv (2008, p. 852)).

In this case the standard Lasso-algorithm is not the first choice (see Section 2.1). In order to overcome the problems described, EN includes an additional $L^2$-norm (ridge) shrinkage parameter into the objective function \((3)\):

$$\hat{\beta} = \arg \min_{\beta} \left[ \| y - X\hat{\beta} \|_2^2 + \lambda_1 \| \hat{\beta} \|_1 + \lambda_2 \| \hat{\beta} \|_2^2 \right]. \quad (12)$$

Thanks to the added parameter in \((12)\) with $\lambda_2 > 0$, the total EN penalty is strictly convex and, therefore, EN regression coefficients tend to be equal
for highly correlated predictors, whereas the Lasso assigns two different (biased) coefficients (Zou and Hastie 2005).

To solve problem (12), one increases the original data set \((y, X)\):

\[
y^* = \begin{pmatrix} y \\ 0 \end{pmatrix}, \quad X^* = (1 + \lambda_2)^{-\frac{1}{2}} \left( \frac{X}{\sqrt{\lambda_2 I}} \right).
\]

Due to the transformation in (13), the new data set \((y^*, X^*)\) has the sample size \(k + n\). Hence, EN can potentially select all \(k\) regressors.

Then the EN solution has the following form:

\[
\hat{\beta}_{EN} = \sqrt{1 + \lambda_2 \hat{\beta}^*},
\]

where:

\[
\hat{\beta}^* = \arg \min_{\beta^*} \left[ \| y^* - X^* \hat{\beta}^* \|_2^2 + \frac{\lambda_1}{\sqrt{1 + \lambda_2}} \| \hat{\beta}^* \|_1 \right].
\]

Thereafter, one takes a grid of values for \(\lambda_2 = \{0, 0.01, 0.1, 1, 10, 100\}\) and perform the LARS-EN algorithm (as it is recommended in Zou and Hastie (2005)) for each of the values, selecting the one with the smallest PE.

### 2.2.2 Adaptive Lasso

Another approach ‘correcting’ the Lasso was introduced by Zou (2006) differentiating the amount of shrinkage for the coefficients. For this a vector of weights \((\hat{\omega})\) is included in (3):

\[
\hat{\beta}_{aLasso} = \arg \min_{\beta} \left[ \| y - X \hat{\beta} \|_2^2 + \lambda \sum_{j=1}^{k} \hat{\omega}_j |\beta_j| \right],
\]

where the weights can be determined either by the OLS regression, \(\hat{\omega}_j = |\hat{\beta}_{OLS}|^{-\nu}\) (if no collinearity is assumed), or by the ridge regression, \(\hat{\omega}_j = |\hat{\beta}_{ridge}|^{-\nu}\) with \(\nu > 0\). In the following only the ‘ridge-weights’ are used since they are more stable in the case of correlated predictors. As recommended by Zou (2006), \(\nu > 0\) can be selected from the grid of values \(\{0.5, 1, 2\}\) using two-dimensional cross-validation (the second tuning parameter is \(\lambda\)).
The objective function in (16) can be easily integrated in the LARS algorithm by defining $X^{**} = X/\hat{\omega}$ and $\beta_{aLasso} = \hat{\beta}^{**}/\hat{\omega}$ (Zou 2006):

$$\hat{\beta}^{**} = \arg \min_{\hat{\beta}} \left[ \| y - X^{**}\hat{\beta} \|_2^2 + \lambda \sum_{j=1}^{k} |\beta_j| \right]. \tag{17}$$

For $n \to \infty$, $\hat{\omega}$'s of 'false'-predictors grow to infinity applying an additional shrinkage for respective coefficients and, therefore, fulfilling the consistency condition (11).

However, similarly to Lasso, aLasso is not consistent for overdetermined linear systems. In addition, for moderate sample sizes ($n$) aLasso may not be dealing efficiently with correlated predictors. To the best of my knowledge, there is a lack of numerical studies on the performance of aLasso under these circumstances (the only exception I am aware of is presented by Zou and Zhang (2009)).

### 2.3 Heuristic optimization methods

As an alternative to the Lasso technique the information criteria (IC) are taken in this study. IC ranks different models according to their fitness, while taking into account a penalty for model complexity. Over the last years IC has become a standard instrument in model selection problems ranging from lag order selection in multivariate linear (VAR and VEC) and nonlinear (MS-VAR) autoregression models to selection between rival nonnested models (Winker 1995).

Consider a vector $\tau$ of the length $k$ with ones and zeros corresponding to selected and not selected regressors. To rank these vectors the Bayesian IC (BIC) and the Hannan-Quinn IC (HQIC) are implemented in this study. Both these criteria have a similar structure:

$$\text{IC} = \ln(\| y - X\hat{\beta} \|_2^2) + f(h, n), \tag{18}$$

where the second term in the right part is a penalty dependent on the number of parameters included ($h$) and on the sample size ($n$). In particular, $h \ln(n)/n$ and $2h \ln(\ln(n))/n$ are the BIC and HQIC penalties.
Imposing some weak assumptions on the model space \((x_i, \varepsilon_i)\) according to the results of Sin and White (1996), it can be shown that the vector \(\tau^i\) that minimizes the IC converges to \(\tau^{true}\) with probability close to 1 as \(n \to \infty\). But for this to be true, it is essential that the penalty term \(f(h, n) \to \infty\) and \(f(h, n)/n \to 0\) as \(n \to \infty\). In this sense, BIC and HQIC are consistent.

In general, the IC in (18) can be described as a \(L^0\)-constraint penalizing not the coefficients’ values, but only their number:

\[
\hat{\beta}_{IC} = \arg \min_{\beta} \left[ \| y - X\hat{\beta} \|_2^2 + \lambda \| \hat{\beta} \|_0 \right].
\] (19)

As noted by Zhao and Yu (2006, p. 2553), the solution of (19) remains consistent even for data sets with correlated regressors since it fulfills the condition (11).

However, since the search space of candidate models in (19) is discrete, the objective function is not necessarily ‘well-behaved’ enough to guarantee a global optimal solution using standard gradient methods, as the Newton or quadratic hill-climbing techniques. In fact, Breiman (2001) demonstrates the so called ‘Rashomon Effect’, where different model specifications with very similar IC values provide different conclusions. Hence, quality and precision of econometric estimation is crucially dependent on detecting the global optimum of (18). The full enumeration of all possible solutions is only feasible for a small \(k\). In the following Monte-Carlo setup (see Section 3 below) the selection is made out of 50 and 100 variables. Since a full enumeration of solutions results in \(2^k\) potential sub-models, the full enumeration is infeasible even using efficient algorithms.

In the last two decades, new nature-inspired optimization methods have become available. These methods are called ‘heuristic’ because of their stochastic nature. However, thanks to the recent advances in heuristic optimization methods, there are efficient algorithms able to select a model with at least a good approximation to the IC optimum. A formal study on the convergence of heuristic algorithms can be found in Maringer and Winker (2009). For an overview of these optimization techniques, see Gilli and Winker (2009). In Savin and Winker (2010) a similar subset selection problem was handled.
by two heuristic algorithms: Threshold Accepting and Genetic Algorithms. Since Genetic Algorithms (GA) provided some better results in terms of both CPU time and solution quality, only GA are considered in the following.

GA are population-based heuristic methods that operate on a set of solutions (population). Thus, GA investigate the search space in many directions simultaneously, so that the probability of getting stuck into a local optimum is reduced.

The members in the GA population (chromosomes) are represented as bit strings, in which each position (gene) has two possible values: 1 and 0. In each generation GA replace parts of a population with new chromosomes (children) aimed to represent better solutions for a given problem. For optimal model selection, the GA pseudocode described in Algorithm 2 is used.

**Algorithm 2 Pseudocode for Genetic Algorithms.**

1: Generate initial population $K$ of solutions, initialize $G$ and $C$
2: for $g = 1$ to $G$ do
3:   Sort chromosomes in $K$
4:   Select $K' \subset K$ (parents), select $K^* \subset K$ (elitist)
5:   initialize $K'' = \emptyset$ (set of children)
6:   for $c = 1$ to $C$ do
7:       Select individuals $x^{\text{parent}1}$ and $x^{\text{parent}2}$ at random from $K'$
8:       Apply cross-over to $x^{\text{parent}1}$ and $x^{\text{parent}2}$ to produce $x^{\text{child}}$
9:       $K'' = K'' \cup x^{\text{child}}$
10:  end for
11:  $K = (K', K'')$
12:  Mutate $K \setminus K^*$ at 5 random points
13: end for

$K$ is a matrix of $p = 500$ initial solutions generated by random distribution of zeros and ones. Thereafter, the population is sorted according to (18). Then, the 50% of the chromosomes with the best target values (parents, $K'$) are transferred to the new population and new chromosomes (children, $K''$) are constructed by crossing them over. Generating children one allows parents with superior objective values to be selected more often (see Savin and Winker (2010)). In this implementation the uniform crossover

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4 This number is considered to be large enough to screen the search space and to allow for effective selection of the best solutions.
mechanism is used. Hence, parents may be split not only at one particular gene, but at each gene. Evidence on advantages of the uniform crossover technique can be found in Fogel (2006) and Savin and Winker (2010).

After a new population is formed, mutation is applied at five random genes with a probability of 50%. All chromosomes in $K$ excepting the ten best (elitist) solutions and the 10 children generated from the elitist solutions by mutation ($K^*$) are mutated. This procedure is repeated for a given number of generations $G = 2000$ (computational resources).

An illustration on the distribution of resulting IC values for 100 Monte-Carlo restarts ($n = 400$, $k = 50$ with only five of them actually involved in generating an artificial response variable) can be found in Figure 1. Increasing $G$ the distribution shifts left and becomes less dispersed (see also Gilli and Winker (2009, page 98)). Since GA are a stochastic method, the algorithm is restarted ten times and the solution with the best IC value is selected.

![Figure 1: Empirical distribution of IC for different values of G.](image)

Figure 1: Empirical distribution of IC for different values of $G$. 

13
3 Monte-Carlo study

In this Section the performance of the Lasso-type methods (Lasso, aLasso, EN) and the one of the subset-selection technique via GA (BIC, HQIC) are compared. The goal of this comparison is to determine how stable the methods are: in what Monte-Carlo set-ups each of them provides superior results (in terms of correctly identified subsets and estimation accuracy) and what is the corresponding CPU time needed.

The Monte-Carlo set-ups below have certain parallels with the scenarios tested in Frank and Friedman (1993), Zou (2006) and Zou and Zhang (2009), making potential comparison of the results possible. However, there are also significant distinctions in the DGP (e.g., amount of noise, portion of relevant regressors) and in the scope of the methods tested (including both the Lasso-type and the heuristic model selection methods).

3.1 Data generating process

In order to compare the performance of the Lasso-type techniques with the GA algorithm implemented, various artificial data sets are generated. These set-ups are tested using different numbers of regressors in a data set and different numbers of observations per regressor ($k = 50$ and $n = 400$, $k = 50$ and $n = 100$ or $k = 100$ and $n = 60$). In the latter case the situation where $k \gg n$ is analyzed.

The covariance matrix $\Sigma$ is set either $\Sigma_{i,j} = 0.5^{|i-j|}$ or $0.75^{|i-j|}$ with $1 \leq i, j \leq k$. In the former case, all off-diagonal elements do not exceed 0.5 ('low correlation'); in the latter one, pairwise highly correlated regressors are generated ('high correlation'). The 'true' regression coefficient vector ($\beta^{mc}$) contains either a small or a large portion of non-zero coefficients ($k^{true} = 5$ or 25, respectively), which are either equal ($\beta_j^{mc} = 1$) or unequal ($\beta_j^{mc} = j^2$). In the latter case $\beta_j^{mc} = (1, 4, 9, 16,...)$.

For each set-up, 50 restarts of the following procedure are performed. First, a set of regressors ($X^{mc}$) with a joint Gaussian distribution and a specified $\Sigma$ is randomly generated. Then, using $\beta^{mc}$ and adding an i.i.d. error term, the response variable ($y^{mc}$) is generated as follows:
\[ y^{mc} = X^{mc} \beta^{mc} + \varepsilon, \quad \varepsilon \sim n(0, \sigma^2), \]  

where \( \sigma^2 \) is the variance of the residuals.

In (20) one chooses \( \sigma \) such that the corresponding signal-to-noise ratio (SNR) is either 5 (‘low noise’) or 0.5 (‘high noise’), where the SNR is given by:

\[ \text{SNR} = \frac{\text{var}(X^{mc} \beta^{mc})^{1/2}}{\sigma}. \]  

3.2 Simulation results

The simulation results are compared using the True Positive Rate (TPR) and the False Negative Rate (FNR) as estimations of a correctly identified model. The mean-squared error (MSE = \( E[(\hat{\beta} - \beta^{mc})' \Sigma (\hat{\beta} - \beta^{mc})] \)) with standard deviations computed over 50 replications given in parentheses are used as a measure of the estimation accuracy. In addition, the CPU time corresponding to a single restart using Matlab 7.7 on a Pentium IV 2.67 GHz is reported.

As one can see in Table 1, Lasso-type solutions perform well identifying the correct subset structure in the scenario with low level of noise (at most, only one false regressor included). It is also clear that in the case of high correlation and low noise level, EN outperforms other Lasso-type methods.

However, in the scenario with high amount of noise, all Lasso-type methods tend to exclude two or three ‘true’ regressors from the solution identified (FNR \( \approx 4\text{-}6\% \)). In this case aLasso performs the best out of the other Lasso-type techniques. If the regressors in the ‘true’ subset are also correlated, some false regressors are selected by all of the Lasso-type estimators. This

5TPR is the percentage of ‘true’ regressors from all variables selected and FNR is the portion of rejected ‘true’ regressors among correctly selected and correctly rejected ones.
6For each of the methods, the averaged results over 50 replications of the procedure are reported.
7This corresponds to the situation when a data set includes the majority of significant predictors which explain \( y \).
8This fact is supported in other simulation studies (see, e.g., Johnson (2009, page 496)).
Table 1: Simulation results for \( n = 400 \), \( k = 50 \), \( k_{true} = 5 \) and \( \beta_{j}^{mc} = 1 \).

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<th>Lasso</th>
<th>EN</th>
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<th>BIC</th>
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</tr>
<tr>
<td>MSE</td>
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<td>4.25</td>
<td>3.30</td>
<td>.77</td>
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<td>5.4s</td>
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</table>

results in a large estimation bias.

In contrast, the results of the heuristic method are not influenced as strongly by the amount of noise in the simulated data sets. In terms of the estimation bias IC via heuristics outperform all Lasso-type solutions in both set-ups with low and high SNR. This is most obvious with the Bayesian IC that provides sparser models in comparison to HQIC. To this end, for small SNR IC via heuristics are better off identifying the 'true' subset (on average, BIC includes or excludes not more than one variable incorrectly).

In terms of the CPU time, the Lasso-type methods have a significant advantage over the heuristic approach. As an example, one Lasso simulation does not last longer than 1s. Since EN and aLasso require a two-dimensional cross-validation, they need 3-5s on average. IC via GA need about 250s per restart for \( n = 400 \). Reducing \( n \) results in a corresponding decline in the CPU time.

In Table 1 the high variance in the estimated bias for aLasso (especially, in the situation with low noise level) is remarkable. In an additional experiment the described set-up is simulated 100 times for \( SNR \in (0.3, 10) \) and the coefficient of variation for all three Lasso-type solutions is measured (Figure 2). Obviously, for \( SNR > 0.5 \) the variation in results for aLasso is much higher than for other Lasso-type methods. Similar results can be obtained for both
ridge- and OLS-weights and are present in all our simulation studies.

In the following one or two characteristics in the simulation set-up presented in Table 1 are changed and only major differences in results are reported. Thus, considering different regression coefficients (Table 2), one can see that the relative supremacy of the heuristic approach has remained. All methods tested under this scenario exclude more correct regressors, which results in a higher MSE.

Increasing the portion of 'true' regressors ($k^{\text{true}} = 25$), one finds that for high SNR heuristics outperform the Lasso-type methods in identifying the correct subset structure (Table 3). There can be two reasons for this. First, due to the stronger parsimony property of the Lasso methods (aLasso excludes correct variables even with the small portion of noise). Second, due to the larger proportion of relevant predictors, the problem of correlated predictors is more challenging. This is evident when one compares the left and the right panels of Table 3. Reducing the SNR leads to a much larger proportion of mistakes in model selection for all methods. Nevertheless, the

This is mainly due to the asymptotic property of the aLasso-weights ($\hat{\omega}_j$) adding some instability in the model estimation. For SNR > 0.5 and, respectively, smaller MSE values this instability becomes more evident.
Table 2: Simulation results for \( n = 400, \, k = 50, \, k_{\text{true}} = 5 \) and \( \beta_{\text{true}}^{mc} = j^2 \).

<table>
<thead>
<tr>
<th></th>
<th>Lasso EN aLasso BIC HQIC</th>
<th>Lasso EN aLasso BIC HQIC</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Low correlation</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TPR</td>
<td>98%</td>
<td>88%</td>
</tr>
<tr>
<td>FNR</td>
<td>1.5%</td>
<td>1.6%</td>
</tr>
<tr>
<td>MSE</td>
<td>15.9</td>
<td>16.4</td>
</tr>
<tr>
<td>CPU</td>
<td>.6s</td>
<td>.6s</td>
</tr>
<tr>
<td><strong>High correlation</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TPR</td>
<td>100%</td>
<td>95%</td>
</tr>
<tr>
<td>FNR</td>
<td>6.7%</td>
<td>6.9%</td>
</tr>
<tr>
<td>MSE</td>
<td>933</td>
<td>989</td>
</tr>
<tr>
<td>CPU</td>
<td>.7s</td>
<td>.6s</td>
</tr>
</tbody>
</table>

Table 3: Simulation results for \( n = 400, \, k = 50, \, k_{\text{true}} = 25 \) and \( \beta_{\text{true}}^{mc} = 1 \).

<table>
<thead>
<tr>
<th></th>
<th>Lasso EN aLasso BIC HQIC</th>
<th>Lasso EN aLasso BIC HQIC</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Low correlation</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TPR</td>
<td>83%</td>
<td>76%</td>
</tr>
<tr>
<td>FNR</td>
<td>0%</td>
<td>0%</td>
</tr>
<tr>
<td>MSE</td>
<td>.58</td>
<td>.65</td>
</tr>
<tr>
<td>CPU</td>
<td>.5s</td>
<td>.5s</td>
</tr>
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<td><strong>High correlation</strong></td>
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<td>71%</td>
</tr>
<tr>
<td>FNR</td>
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</tr>
<tr>
<td>CPU</td>
<td>.6s</td>
<td>.7s</td>
</tr>
</tbody>
</table>

If one reduces the sample size \((n = 100)\), the Lasso-type methods (except aLasso) are less affected by the asymptotic property than IC via heuristics (Table 4). In the case of low level of noise, heuristics are still better off in terms of MSE, although they accept significantly more false regressors. But for high noise level Lasso-type methods surpass IC via GA in terms of the estimation bias. In general, this is good evidence that Lasso are more

10Due to the higher \( k_{\text{true}} \), the heuristic requires more CPU time (approximately 450s) identifying all 'true' predictors under low noise and estimating their regression coefficients.

11An exception is constituted for the case with correlated predictors: since the Lasso...
suitable for small \( n \) (see also Hsu et al. (2007, page 3649)).

Table 4: Simulation results for \( n = 100, k = 50, k_{\text{true}} = 5 \) and \( \beta_j^{\text{mc}} = 1 \).

<table>
<thead>
<tr>
<th></th>
<th>Lasso</th>
<th>EN</th>
<th>aLasso</th>
<th>BIC</th>
<th>HQIC</th>
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<th>EN</th>
<th>aLasso</th>
<th>BIC</th>
<th>HQIC</th>
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<tbody>
<tr>
<td><strong>Low noise</strong></td>
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<td></td>
<td></td>
</tr>
<tr>
<td>TPR</td>
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<td>91%</td>
<td>99%</td>
<td>77%</td>
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<td>81%</td>
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</tr>
<tr>
<td>FNR</td>
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<td>0%</td>
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<td>0%</td>
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<td>0%</td>
</tr>
<tr>
<td>MSE</td>
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<td>.24</td>
<td>.23</td>
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<td>.09</td>
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<td><strong>High correlation</strong></td>
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<td></td>
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<td></td>
<td></td>
<td></td>
</tr>
<tr>
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<td>65%</td>
<td>45%</td>
<td>49%</td>
<td>30%</td>
<td>60%</td>
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<td>27%</td>
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<td>27%</td>
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<tr>
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<td>7.3%</td>
<td>7.4%</td>
<td>5.5%</td>
<td>5.2%</td>
<td>7.2%</td>
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</tr>
<tr>
<td>MSE</td>
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<td>5.19</td>
<td>5.15</td>
<td>5.61</td>
<td>9.95</td>
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<td>5.57</td>
<td>5.47</td>
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<td>111s</td>
</tr>
</tbody>
</table>

Finally, considering an overdetermined linear system one finds that the performance of all methods dramatically decreases (Table 5). This is more evident for the heuristic approach. The case with \( k \gg n \) can result in extremely small RSS values if a large number of available regressors (\( k \sim n \)) is included. As the IC’s natural logarithm goes to minus infinity, the penalty on model complexity remains in the same (former) order of magnitude. Hence, the resulting difference in IC ‘compensates’ incorrect variables to be included by GA.\(^{12}\) An illustration of this effect is presented in Figure 3. In the left plot with \( n = 400 \), GA identifies a smaller IC value (dashed line) than the one attributed to the ‘true’ subset structure (‘IC-true’). The smaller the \( n \), the larger the difference between the two values. In the extreme case with \( k \gg n \) (right plot) this difference becomes much more apparent.

Consequently, the real limitation of the heuristic approach is the objective function \(^{12}\) that is not suitable for \( k \gg n \), while GA algorithm performs well in both set-ups (for more discussion on this see Appendix). In the set-up with \( k \gg n \), Lasso-type methods (in particular, Lasso and EN) are superior model selection strategies in terms of both correctly identified subset structures and estimated bias\(^{13}\)

\(^{12}\) A similar finding is also made for the Akaike information criterion.

\(^{13}\) Note that in contrast to Zou and Hastie (2005) and Zou and Zhang (2009), no pre-
Table 5: Simulation results for $n = 60$, $k = 100$, $k^{true} = 5$ and $\beta_{ij}^{mc} = 1$.

<table>
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<td>4.9s</td>
<td>5.4s</td>
<td>1339s</td>
<td>1091s</td>
</tr>
</tbody>
</table>

4 Application on a cross-country growth model

To illustrate the model selection techniques, let us apply them to an actual empirical problem, using the real per capita GDP growth rate over 1960-1992 and a series of country’s characteristics evaluated for 1960. The data set was first tested and described in detail by Sala-i-Martin (1997). Due to a large number of missing observations, Fernandez et al. (2001) reduce the original screening that reduces the dimensionality of the problem is employed in this study (as e.g., Sure Independent Screening). Thus, only the methods described in Section are considered.

A set of characteristics is selected that best explains the GDP growth rate within a standard linear regression model.
data set from 134 countries and 62 regressors to 72 and 42, respectively.

The data was used in a series of studies applying different model selection strategies. The most interesting for us (for comparative reasons) are the application of genetic algorithms by Acosta-Gonzalez and Fernandez-Rodriguez (2007) and adaptive Lasso by Schneider and Wagner (2009).

A brief summary of the results for the data set with a total number of regressors included \((h)\) by each strategy is presented in Table 6 (see Table 8 in Appendix for a complete version of the results). As one can see, BIC via GA, Lasso and EN include more than half of the available regressors in the final solution. Comparing their model fits, the IC has the highest \(R^2\) adjusted with the smaller subset of predictors.\(^{15}\) This can be due to a larger number of incorrect variables included by the Lasso-type methods (see results in Table 3). Based on this and together with our Monte-Carlo simulations, the model estimation obtained via GA is considered as the most accurate one in this particular example. Due to a potentially large portion of relevant regressors and high pairwise correlation between certain variables (e.g., for equipment investment and life expectancy it is above 0.64), EN is seen to outperform the other Lasso-type methods.\(^{16}\)

\(^{15}\)In contrast, aLasso rather excludes some relevant regressors, which results in the smaller goodness-of-fit.

\(^{16}\)In our application partly different results are obtained in comparison to the ones in
Acosta-Gonzalez and Fernandez-Rodriguez (2007) try to avoid over-parametrization with an adjusted BIC (18) by doubling its penalty on model complexity. They come up with a smaller model subset (see BIC(adj.)). By employing Algorithm 2 for GA, the same model as in Acosta-Gonzalez and Fernandez-Rodriguez (2007) is identified.

In Table 8 two out of three regressors always included by Sala-i-Martin (1997) are also selected by all the model selection strategies: life expectancy and GDP per capita. In contrast, there is less evidence for primary school enrollment to be retained in the model. This finding is also supported by Fernandez et al. (2001).

5 Conclusions and outlook

The model specification step has a vital role for the further regression analysis, since any ad-hoc or intuitive decisions can reduce the estimation accuracy or introduce an estimation bias. In this study the Lasso-type (Lasso, adaptive Lasso, elastic net) and a heuristic model selection strategy are compared. First, one describes the implementation of all methods underlining their strengths and weaknesses. Second, an illustration of their performances based on several Monte-Carlo experiments is provided. Finally, the methods are implemented on real empirical data and their results are contrasted.

One finds that an application of the Lasso modifications has some influence on its resulting performance in terms of both subset selection correctness and estimation bias. However, this influence is rather marginal in comparison to other model selection methods, in particular, heuristic optimization.

In general, the Lasso-type techniques provide sparser solutions than the heuristic approach. They can better identify irrelevant predictors in a final subset, but exclude more relevant ones. As a result, in most of the simulated set-ups the Lasso methods exhibit a larger estimation bias. If the portion of relevant regressors in a given data set is large or available regressors can explain the indicator of interest to a large extent (‘small noise’), the supremacy

Schneider and Wagner (2009). This is due to another choice of tuning parameters made. In particular, Schneider and Wagner (2009) employ OLS-weights and set $v$ equal to one.
of the heuristics becomes more apparent.

Based on the simulated experiments, one can consider the Lasso methods more suitable for data sets with small sample sizes. In contrast, application of heuristics in this case is constrained by the asymptotic property of IC.

The Lasso methods have a significant advantage over heuristic methods in terms of the CPU time required. Although, as it is demonstrated in this study, nowadays IC via heuristics can be optimized using reasonable computational time.

In the future one can compare the methods discussed with the adaptive elastic net (Zou and Zhang 2009) that combines strengths of the elastic net and the adaptive lasso, or with the adaptive ridge selector (Armagan and Zaretzki forthcoming) that differentiates amounts of shrinkage according to t-statistics. An alternative is to test an application of heuristic methods on the generalized $L^q$-norm approach with $0 < q < 1$.

Acknowledgements  Valuable comments and suggestions from Peter Winker, Thomas Wagner, Marianna Lyra and Henning Fischer are gratefully acknowledged. All remaining shortcomings are my responsibility.

References


6 Appendix

Extensively simulating with different forms of IC (with absolute values of the logarithm and the use of RSS’s absolute value instead of its logarithm in conjunction with a re-scaled penalty for model complexity) one can find an 'adjusted' IC form suitable for the $k \gg n$ case. For example, one can take RSS absolute value and adjust the penalty term via a data-driven multiplicator $\kappa$ set equal to 20 or 1600 (depending on the SNR):

$$IC = \| y - X\hat{\beta} \|^2_2 + \kappa \ln(n)/n,$$

(22)

In the result, one can obtain much better results for the IC via GA (Table 7). However, this form of the IC is no longer 'universal' and has to be calibrated for each particular data set.

Table 7: Simulation results for $n = 60$, $k = 100$, $k^{true} = 5$ and $\beta_j^{true} = 1$.

<table>
<thead>
<tr>
<th>Lasso</th>
<th>EN</th>
<th>aLasso</th>
<th>BIC</th>
<th>HQIC</th>
<th>Lasso</th>
<th>EN</th>
<th>aLasso</th>
<th>BIC</th>
<th>HQIC</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>TPR</td>
<td>61%</td>
<td>75%</td>
<td>49%</td>
<td>90%</td>
<td>62%</td>
<td>43%</td>
<td>54%</td>
<td>46%</td>
<td>93%</td>
</tr>
<tr>
<td>FNR</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>0%</td>
<td>0.1%</td>
<td>0%</td>
</tr>
<tr>
<td>MSE</td>
<td>.18</td>
<td>.16</td>
<td>.05</td>
<td>.15</td>
<td>.16</td>
<td>.15</td>
<td>.13</td>
<td>.04</td>
<td>.07</td>
</tr>
<tr>
<td></td>
<td>(.10)</td>
<td>(.09)</td>
<td>(.04)</td>
<td>(.10)</td>
<td>(.09)</td>
<td>(.08)</td>
<td>(0.51)</td>
<td>(.03)</td>
<td>(.04)</td>
</tr>
<tr>
<td>CPU</td>
<td>0.7s</td>
<td>5.2s</td>
<td>5.4s</td>
<td>174s</td>
<td>189s</td>
<td>0.7s</td>
<td>5.3s</td>
<td>5.7s</td>
<td>168s</td>
</tr>
</tbody>
</table>

Low correlation

| TPR   | 38% | 38%    | 19% | 40%  | 24%   | 32%| 32%    | 13% | 26%  | 14% |
| FNR   | 4.2%| 4.2%   | 3.7%| 3.9% | 3.9%  | 4.2%| 4.2%   | 3.9%| 4.1% | 4.1%|
| MSE   | .28 | .51    | 9.4 | 3.40 | 7.51  | .25| .36    | 28.78| 4.51 | 10.59|
| CPU   | .7s | 4.8s   | 4.5s| 70s  | 75s   | .8s | 4.9s   | 5.4s| 70a  | 76s |

High correlation
Table 8: Results for the cross-country growth model.

<table>
<thead>
<tr>
<th></th>
<th>BIC</th>
<th>BIC(adj.)</th>
<th>Lasso</th>
<th>EN</th>
<th>aLasso</th>
</tr>
</thead>
<tbody>
<tr>
<td>Constant</td>
<td>0.0797</td>
<td>0.0419</td>
<td>0.0206</td>
<td>0.0399</td>
<td>0.0998</td>
</tr>
<tr>
<td>Primary school enrollment</td>
<td>0.0249</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Life expectancy</td>
<td>0.0009</td>
<td>0.0010</td>
<td>0.0010</td>
<td>0.0009</td>
<td>0.0011</td>
</tr>
<tr>
<td>Log of per capita GDP</td>
<td>-0.0188</td>
<td>-0.0130</td>
<td>-0.0111</td>
<td>-0.0126</td>
<td>-0.0177</td>
</tr>
<tr>
<td>Fraction of GDP in mining</td>
<td>0.0328</td>
<td>-</td>
<td>0.0337</td>
<td>0.0370</td>
<td>-</td>
</tr>
<tr>
<td>Degree of capitalism</td>
<td>-</td>
<td>0.0023</td>
<td>-0.0058</td>
<td>-0.0064</td>
<td>-</td>
</tr>
<tr>
<td>Number of years open economy</td>
<td>-</td>
<td>0.0176</td>
<td>0.0056</td>
<td>0.0036</td>
<td>-</td>
</tr>
<tr>
<td>Fraction speaking English</td>
<td>-0.0078</td>
<td>-</td>
<td>-0.0058</td>
<td>-0.0064</td>
<td>-</td>
</tr>
<tr>
<td>Fraction speaking foreign language</td>
<td>-</td>
<td>-</td>
<td>-0.0008</td>
<td>-0.0006</td>
<td>-</td>
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<tr>
<td>Exchange rate distortions</td>
<td>-</td>
<td>-</td>
<td>3.3 × 10⁻⁶</td>
<td>2.4 × 10⁻⁶</td>
<td>-</td>
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<tr>
<td>Equipment investment</td>
<td>0.1511</td>
<td>0.2181</td>
<td>-</td>
<td>0.0036</td>
<td>-</td>
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<tr>
<td>Non-equipment investment</td>
<td>0.0295</td>
<td>-</td>
<td>0.0108</td>
<td>0.0256</td>
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<tr>
<td>Std dev of black market premium</td>
<td>-</td>
<td>-</td>
<td>2.4 × 10⁻⁶</td>
<td>1.8 × 10⁻⁶</td>
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<tr>
<td>Outward orientation</td>
<td>-0.0035</td>
<td>-</td>
<td>-0.0021</td>
<td>-0.0023</td>
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<td>Black market premium</td>
<td>-0.0055</td>
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<td>-0.0037</td>
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<tr>
<td>Total area of the country</td>
<td>-</td>
<td>-</td>
<td>2.5 × 10⁻⁸</td>
<td>3.3 × 10⁻⁸</td>
<td>−6.1 × 10⁻¹⁰</td>
</tr>
<tr>
<td>Latin American dummy</td>
<td>-0.0127</td>
<td>-</td>
<td>-0.0050</td>
<td>-0.0055</td>
<td>-0.0118</td>
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<td>Sub-Saharan dummy</td>
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<td>-0.0091</td>
<td>-0.0131</td>
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<td>Higher education enrollment</td>
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<td>-</td>
<td>-</td>
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<tr>
<td>Public education share</td>
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<td>0.0012</td>
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<td>Revolutions and coups</td>
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<td>-</td>
<td>-0.0024</td>
<td>-0.0033</td>
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<tr>
<td>War dummy</td>
<td>-</td>
<td>-</td>
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<td>-0.0019</td>
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<tr>
<td>Political rights</td>
<td>-</td>
<td>-</td>
<td>-0.0016</td>
<td>-0.0019</td>
<td>-</td>
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<tr>
<td>Civil liberties</td>
<td>-0.0028</td>
<td>-</td>
<td>0.0019</td>
<td>0.0017</td>
<td>-0.0016</td>
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<tr>
<td>Absolute latitude</td>
<td>-</td>
<td>-</td>
<td>5.0 × 10⁻⁶</td>
<td>4.5 × 10⁻⁶</td>
<td>-</td>
</tr>
<tr>
<td>Average age of the population</td>
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<td>-</td>
<td>-0.0011</td>
<td>0.0015</td>
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<tr>
<td>British colony dummy</td>
<td>0.0079</td>
<td>-</td>
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<tr>
<td>Fraction of buddhist</td>
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<td>-0.0024</td>
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<tr>
<td>Fraction of catholic</td>
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<td>0.0577</td>
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<td>0.0460</td>
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<td>French colony dummy</td>
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<td>Fraction of hindu</td>
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<tr>
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<tr>
<td>Fraction of muslim</td>
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<td>0.0118</td>
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<td>0.0038</td>
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<tr>
<td>Primary exports</td>
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<td>-0.0039</td>
<td>-0.0040</td>
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<tr>
<td>Fraction of protestant</td>
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<td>-0.0136</td>
<td>-0.0108</td>
<td>-0.0111</td>
<td>-</td>
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<td>Rule of law</td>
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<td>-</td>
<td>0.0103</td>
<td>0.0108</td>
<td>0.0096</td>
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<td>Spanish colony dummy</td>
<td>0.0140</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Growth rate of population</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Ratio workers to population</td>
<td>-</td>
<td>-</td>
<td>-0.0126</td>
<td>-0.0113</td>
<td>-</td>
</tr>
<tr>
<td>Labor force</td>
<td>-3.8 × 10⁻⁸</td>
<td>-2.6 × 10⁻⁹</td>
<td>7.9 × 10⁻⁹</td>
<td>-4.9 × 10⁻⁹</td>
<td>-</td>
</tr>
<tr>
<td>R²</td>
<td>95%</td>
<td>81%</td>
<td>88%</td>
<td>91%</td>
<td>72%</td>
</tr>
<tr>
<td>R²(adjusted)</td>
<td>92%</td>
<td>79%</td>
<td>78%</td>
<td>81%</td>
<td>67%</td>
</tr>
</tbody>
</table>